

# Fluctuations in Plasma and the Test Particle Model

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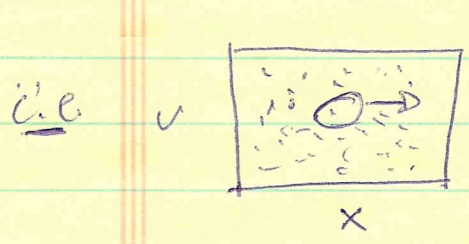
# i) Basic Ideas - Equilibrium Fluctuations

→ plasma:

- $1/n\lambda_D^3 \ll 1 \Rightarrow$  many particles in Debye sphere
- $k_B T \gg e^2/r \Rightarrow$  thermal energy dominates electrostatic energy

→ Equilibrium: Balanced

- absorption vs. emission (equivalent)
- fluctuation vs. dissipation



① emission: discrete particle in plasma fluid emits waves

$$\nabla \cdot \underline{D} = \nabla \cdot \underline{\epsilon} \underline{E} = 4\pi n_0 q d(\underline{x} - \underline{x}(t))$$

i.e. → aka! boat wake on water  
→ Cerenkov emission

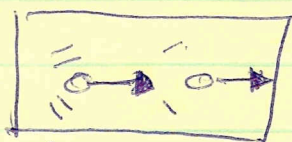
∴ discrete emission ⇒ fluctuation

i.e. - particle kinetic energy coupled to wave energy  
- Cerenkov emission ⇒ particle slowing down



- ② Cerenkov emitted waves damp  
 via  $\rightarrow$  Landau damping  
 $\rightarrow$  in/on Vlasov fluid (over Landau damping for  $v \rightarrow 0$ )

c.e.



emitted waves damp  $\rightarrow$  { absorption  
dissipation }  $>$  heats particles

So, conceptual picture of thermal equilibrium  
 Fluctuations is detailed balance of:

$\rightarrow$  Cerenkov emission of waves from individual  
 discrete particles

$\rightarrow$  absorption of waves via Landau damping  
 on Vlasov fluid

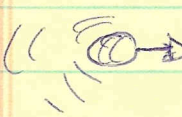
NB: <sup>①</sup> Here, assume periodic B.C.'s  $\rightarrow$  no radiative damping,  
 outgoing waves, etc.

(Note in this picture, each particle plays  
 a dual role (i.e. "double agent")):


② In general, take damping length finite  
 $\underline{\text{d.e.}} \quad \lambda_{\text{damp}} \sim \frac{\omega}{k} / |v_{\text{th}}| < L_{\text{system}}$

As:

- "emitter": a discrete particle moving along some specified (unperturbed) orbit

d.e.  an identifiable 'pea' in a 'pea soup' composed of other peas.

- "absorber": an element of the Vlasov fluid responding to, and Landau damping, emission from (other) discrete particles

d.e.  a "crushed pea" element of the "pea soup" of the Vlasov fluid.

so  
 $\Rightarrow$  equilibrium plasma = soup/gas of 'dressed' test particles

$\downarrow$   
 Vlasov fluid  
 & screening

$\Rightarrow$  "test particle model"

$\rightarrow$  every pea in the soup acts like soup for all the other peas ----



## Note: Useful Analogy

	Brownian Motion	Equilibrium Plasma
Fluctuations	$\langle \tilde{v}^2 \rangle_\omega$	$\langle \tilde{E}^2 \rangle_{k, \omega}$
Exciton	$\omega$ -mode	$k, \omega(k) \rightarrow$ plasma waves
Emission/Source	$\langle \tilde{f}^2 \rangle$ - fluid thermal force	particle discreteness
Absorption/Damping	$B \rightarrow$ Stokes Drag on Particle	$E_{IM} \leftrightarrow$ Landau Damping of Collective Modes

n.b. : "Brownian Motion"

$$\frac{d\tilde{v}}{dt} + \beta \tilde{v} = \frac{f}{m}$$

# (b) Test Particle Model - Fluctuation Spectrum

→ As noted before, basic idea is that:

- each particle both a 'discrete emitter' and participant in laser fluid screening cloud
- fluctuations weak → unperturbed orbits valid.

if consider stationary cond:

$$\delta F = F^c + \tilde{F}$$

↓ coherent laser response (screening)      ↓ discrete particle source      Calc! Debye Calculation)

$$\delta f = \frac{|e| \tilde{E}_{k, \omega}}{m (-i(\omega - kv))} \partial \langle F \rangle / \partial v + |e| \delta(x - x(t)) \delta(v - v(t))$$

↓ coherent response      ↓ discreteness source.

$$\partial^2 \phi = 4\pi n_0 |e| \int dv \delta f = 4\pi n_0 |e| \int dv F^c + 4\pi n_0 |e| \int dv \tilde{F}$$



$$\Rightarrow \vec{\phi}_{k, \omega} = \frac{4\pi n_0 e l}{k^2} \int dv \vec{F} / \epsilon(k, \omega)$$

$$\epsilon(k, \omega) = 1 + \frac{\omega_p^2}{k} \int dv \frac{\partial \langle f \rangle / \partial v}{\omega - kv}$$

using u.p.o. :

$$\begin{aligned} \int dv \vec{f}_k &= \int dx e^{-ikx} |e| \delta(x - x(t)) \\ &= |e| e^{-ikvt} \end{aligned}$$

$$\underline{\underline{\text{So}}} \vec{\phi}_k(t) = \underline{\underline{\epsilon^{-1}(k, t)}} \frac{4\pi n_0 e l}{k^2} e^{-ikvt}$$

Note: strictly speaking, have:

$$\underline{\underline{\epsilon(k, t)}} \vec{\phi}_k(t) = \frac{4\pi n_0 e l}{k^2} e^{-ikvt}$$

$$\underline{\underline{\text{So}}} \phi_k(t) = \underline{\underline{\epsilon^{-1}(k, t)}} \frac{4\pi n_0 e l}{k^2} e^{-ikvt} + \phi_k^{\text{homog.}} e^{-i\omega_k t}$$

↓  
driven solution  
(discreteness)

↓  
homogeneous  
solution

$$\omega_n = \omega_r(k) + i\omega_i(k) \quad \rightarrow \text{eigenmode freq}$$

Now, - time asymptotically ....

- for  $\omega_i(k) < 0 \Rightarrow$  collective modes damped ....

$\Rightarrow$  only discreteness driven solutions persist ....

Catch:  $\Rightarrow$  For  $\omega_i \lesssim 0 \Rightarrow$  i) need wait quite a long time.  
ii) for sufficient source strength, amplification to nonlinearity occurs ....

n.b. moving toward, but not to, marginal stability  $\Rightarrow \text{Im} \omega \rightarrow \infty$

$\rightarrow$  if unstable modes, require ultimate nonlinear damping to balance noise  
i.e.  $\epsilon_{IM} = \epsilon_{IM}(k, \omega, \langle \hat{\phi}^2 \rangle)$  ....

"noise" = thermal + nonlinear, in that case  
....



Proceeding, then test particle model  $\Rightarrow$

$$\langle \hat{\phi}^2 \rangle_{k, \omega} = \left( \frac{4\pi n_0 |e|}{k^2} \right)^2 \int dV_1 \int dV_2 \frac{\langle \tilde{F}(t_1) \tilde{F}(t_2) \rangle_{k, \omega}}{|\epsilon(k, \omega)|^2}$$

, all content  $\rightarrow \langle \tilde{F}^2 \rangle_{k, \omega}$  (abbreviation)  
 $\rightarrow \epsilon(k, \omega)$

Now, for discreteness noise:

$$\tilde{F} = \frac{1}{\Omega} \sum_{i=1}^N d(x_i - X_i(t)) d(v - v_i(t))$$

$\rightarrow$

$$\left. \begin{aligned} X_i(t) &= X_{i0} + v_i t \\ v_i(t) &= \text{const} \end{aligned} \right\} \text{u.p.o.}$$

$\rightarrow$  assume (discrete) uncorrelated test particles, so:

$$\text{so } \langle \rangle = n \int d\underline{x}_0 \int d\underline{v}_i \langle f(v_i) \rangle$$

}  $\odot$  Maxwellian

i.e. simple avg. over equilibrium distribution

$$(k_B T \gg e^2 / \bar{r})$$

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$$\langle \tilde{f}(a) \tilde{f}(b) \rangle = n \int dx_i \int dv_i \left[ \frac{1}{n} \sum_{i=1}^N \delta(\underline{x}_i - \underline{x}_i(t)) \delta(\underline{v}_i - \underline{v}_i(t)) \right] * \left[ \frac{1}{n} \sum_{j=1}^N \delta(\underline{x}_j - \underline{x}_j(t)) \delta(\underline{v}_j - \underline{v}_j(t)) \right] \langle f \rangle$$

$$= \frac{1}{n} \delta(\underline{x}_1 - \underline{x}_2) \delta(\underline{v}_1 - \underline{v}_2) \langle f \rangle$$

as avg. vanishes unless  $\begin{pmatrix} \underline{x}_i \\ \underline{v}_i \end{pmatrix} = \begin{pmatrix} \underline{x}_j \\ \underline{v}_j \end{pmatrix}$

M.B.  $\ddagger$  Uncorrelated test particles can only correlate with themselves...

$$\text{so } \boxed{\langle \tilde{f}(a) \tilde{f}(b) \rangle = \frac{\langle f \rangle}{n} \delta(\underline{x}_1 - \underline{x}_2) \delta(\underline{v}_1 - \underline{v}_2)}$$

Discreteness  
Correlation

See Pg. 11 for further details ...